

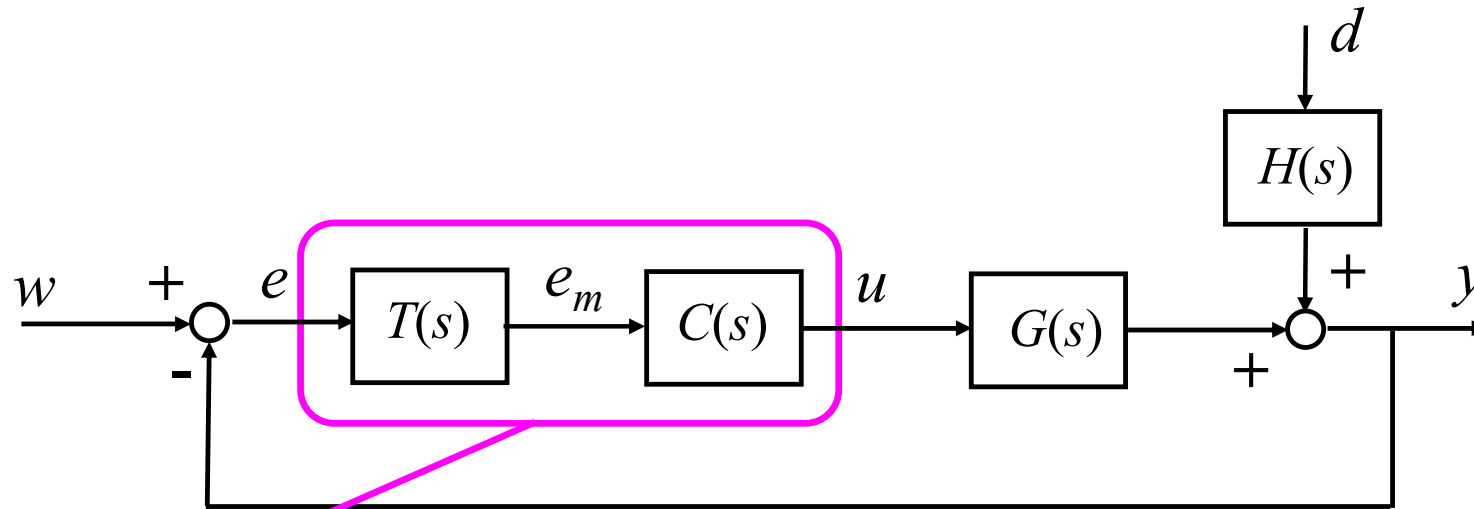
# Lezione 16. Analisi delle prestazioni di sistemi retroazionati (a)

## Introduzione

# Schema

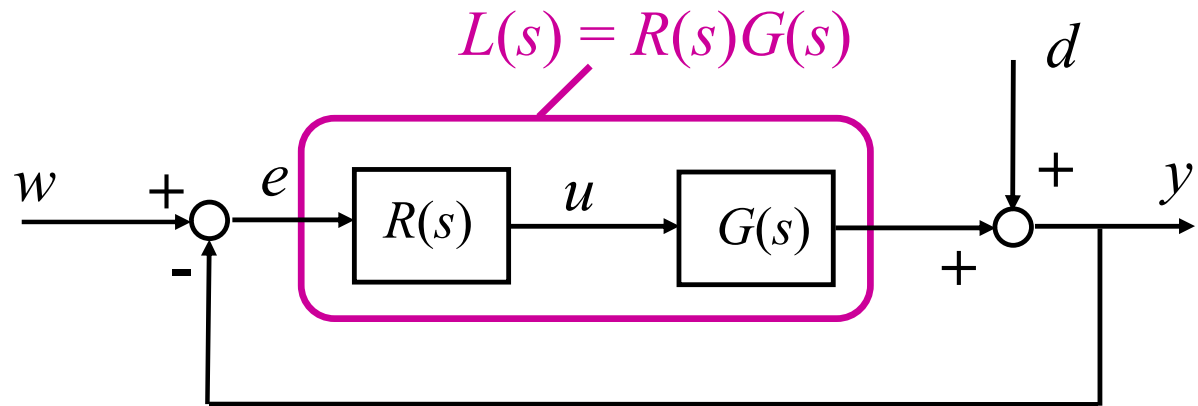
1. Funzioni di trasferimento in anello chiuso
2. Funzioni di sensitività
3. Rappresentazioni equivalenti
4. Esempio

# 1. Funzioni di trasferimento in anello chiuso



$$R(s) = T(s)C(s)$$

per il momento supponiamo  $H(s) = 1$



$$\frac{Y(s)}{W(s)} = \frac{L(s)}{1 + L(s)} = F(s)$$

$$\frac{Y(s)}{D(s)} = \frac{1}{1 + L(s)} = S(s)$$

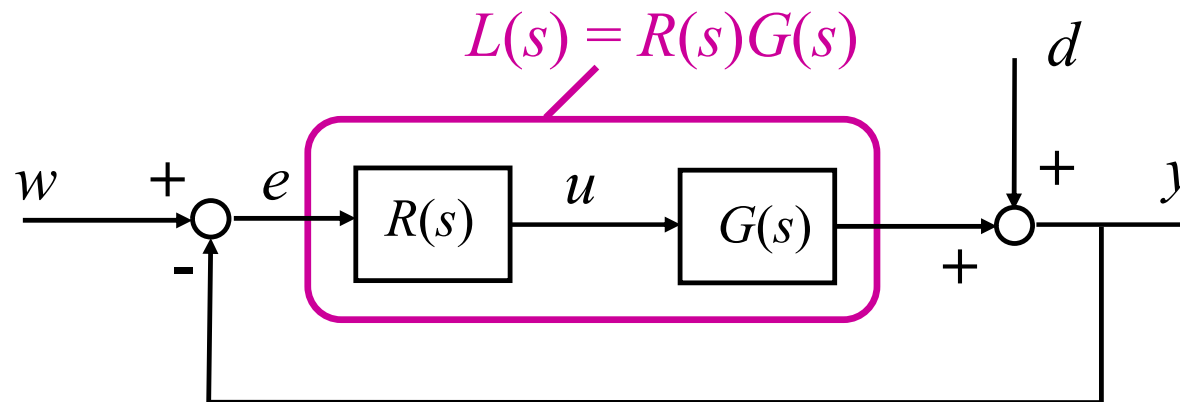
$$\frac{E(s)}{W(s)} = \frac{1}{1 + L(s)} = S(s)$$

$$\frac{E(s)}{D(s)} = \frac{-1}{1 + L(s)} = -S(s)$$

$$\frac{U(s)}{W(s)} = \frac{R(s)}{1 + L(s)} = Q(s)$$

$$\frac{U(s)}{D(s)} = \frac{-R(s)}{1 + L(s)} = -Q(s)$$

## 2. Funzioni di sensitività



$$F(s) = \frac{L(s)}{1 + L(s)}$$

funzione di sensitività complementare

$$S(s) = \frac{1}{1 + L(s)}$$

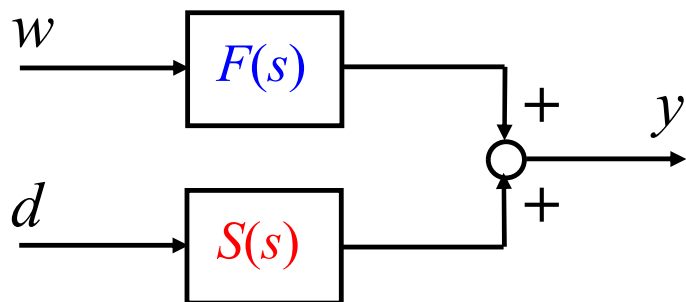
funzione di sensitività

$$Q(s) = \frac{R(s)}{1 + L(s)}$$

funzione di sensitività del controllo

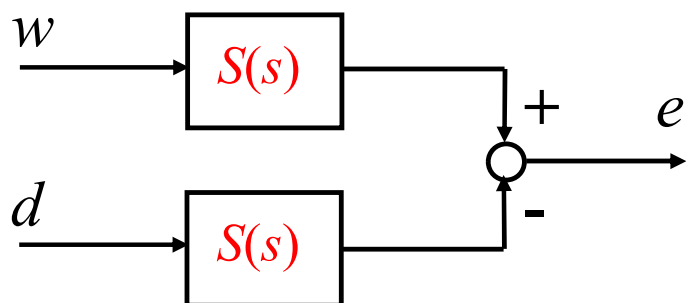
### 3. Rappresentazioni equivalenti

prestazioni  
ideali



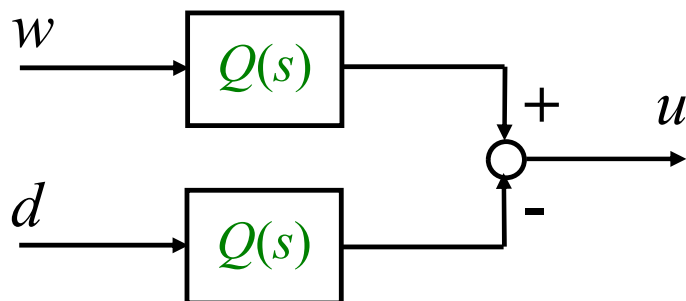
$$F(s) = \frac{L(s)}{1 + L(s)}$$

$\sim 1$



$$S(s) = \frac{1}{1 + L(s)}$$

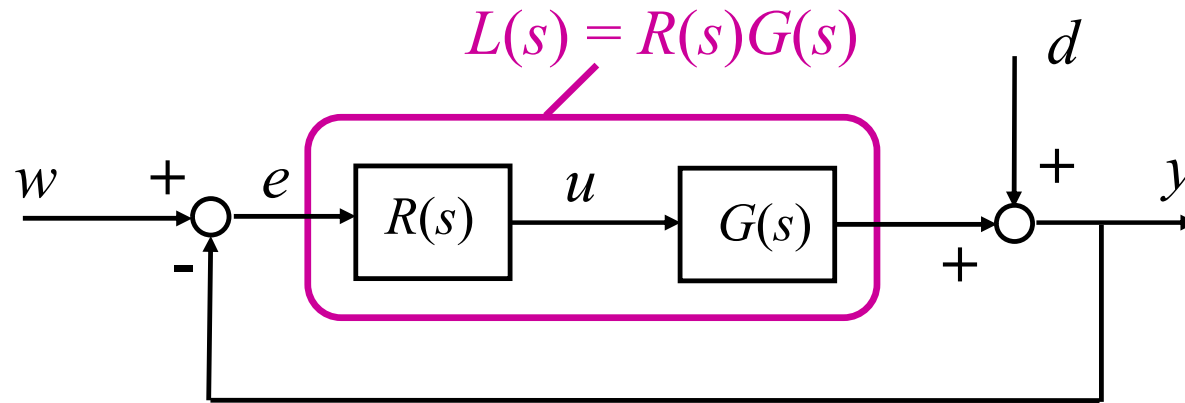
$\sim 0$



$$Q(s) = \frac{R(s)}{1 + L(s)}$$

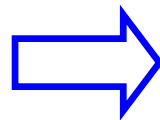
$\sim 0$

# Esempio



$$R(s) = \frac{10}{s}$$

$$G(s) = \frac{1}{s+2}$$



$$L(s) = R(s)G(s) = \frac{10}{s(s+2)}$$

$$F(s) = \frac{L(s)}{1+L(s)} = \frac{\frac{10}{s(s+2)}}{1+\frac{10}{s(s+2)}} = \frac{10}{s^2+2s+10}$$

$$S(s) = \frac{1}{1+L(s)} = \frac{1}{1+\frac{10}{s(s+2)}} = \frac{s(s+2)}{s^2+2s+10}$$

$$Q(s) = \frac{R(s)}{1+L(s)} = \frac{\frac{10}{s}}{1+\frac{10}{s(s+2)}} = \frac{10(s+2)}{s^2+2s+10}$$

